

Rotating Field Coordinates into GPS or Total Station Coordinates

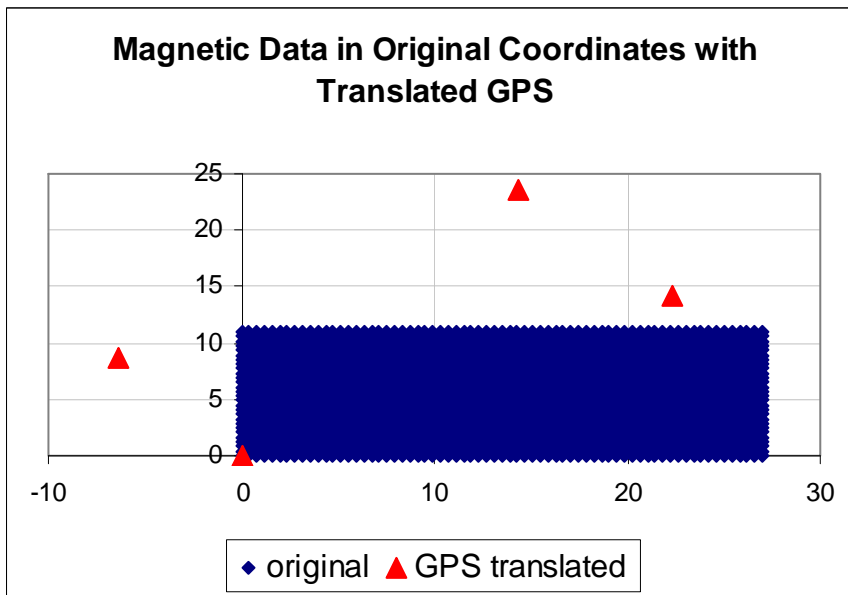
Assumptions:

- Magnetic grids are collected in a rectangular grid starting at X=0, Y=0.
- The corners are known in another coordinate system (e.g. GPS or total station); axes need not be aligned.
- The starting spreadsheet has X, Y, and TMI as in the figure to the right.

Steps:

- Make room for 4 additional columns
 1. X rotated
 2. Y rotated
 3. X translated
 4. Y translated
- Add three tables to the spreadsheet:
 1. GPS corners
 2. Grid Corners
 3. Rotated grid corners (to be filled in later)
- Translate the GPS coordinates to the origin:
 1. $X_translated = X - \text{southwest corner X value}$
 2. $Y_translated = Y - \text{southwest corner Y value}$
- Make a map (graph) of the original data points and the translated GPS points

	A	B	C	
1	x	y	TMI	x
2	0.000	0.021	97.42549	
3	0.000	0.427	95.10713	
4	0.000	0.833	91.99171	
5	0.000	1.239	84.16308	
6	0.000	1.644	73.34015	
7	0.000	2.050	73.80244	
8	0.000	2.456	74.14364	
9	0.000	2.862	47.6227	
10	0.000	3.268	22.59538	
11	0.000	3.674	20.95218	
12	0.000	4.080	4.896253	



- Look at the figure and guess the needed amount of rotation. In this example it is about 30°.
- Using the X_rotated and Y_rotated columns, rotate the original (x, y) values by the guessed amount of rotation. The rotation equations are:

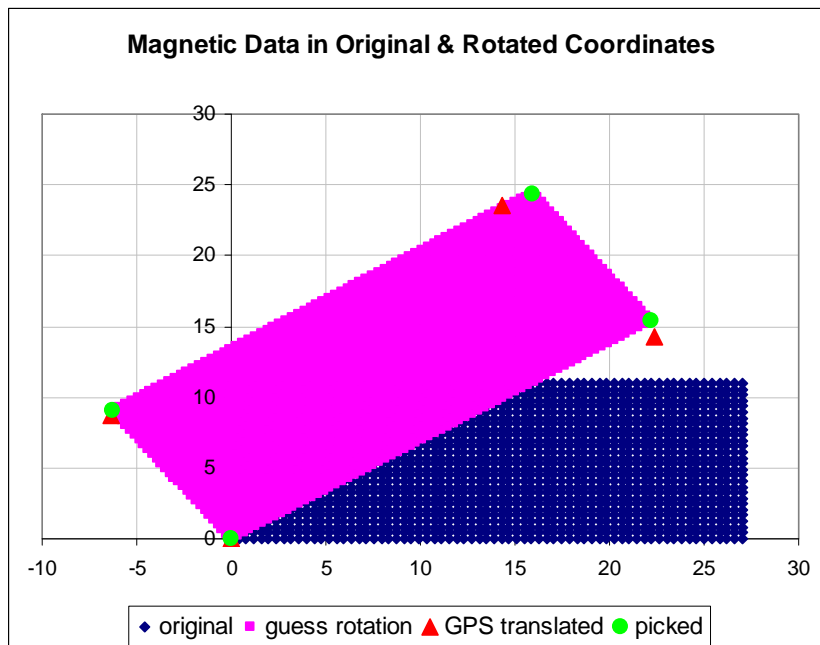
$$X' = x \cdot \cos(\text{Rot_angle}) + y \cdot \sin(\text{Rot_angle})$$

$$Y' = -x \cdot \sin(\text{Rot_angle}) + y \cdot \cos(\text{Rot_angle})$$

remember that Excel requires angles in radians when using trigonometric functions.

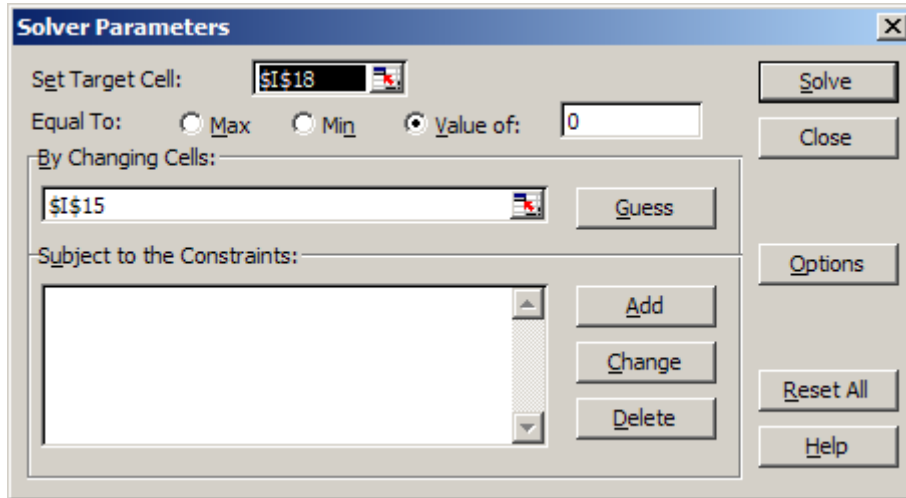
	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
1	x	y	TMI	X rotated1	Y rotated1	X trans	Y trans		GPS corners with error		GPS Translated				
2	0.000	0.021	97.42549	-0.012	0.017	454116.256	5427675.278		East	North					
3	0.000	0.427	95.10713	-0.243	0.351	454116.025	5427675.612		SE	454138.61	5427689.49	SE	22.34	14.23	
4	0.000	0.833	91.99171	-0.474	0.685	454115.794	5427675.946		SW	454116.27	5427675.26	SW	0.00	0.00	
5	0.000	1.239	84.16308	-0.705	1.018	454115.563	5427676.279		NW	454109.92	5427683.96	NW	-6.35	8.70	
6	0.000	1.644	73.34015	-0.936	1.352	454115.332	5427676.613		NE	454130.61	5427698.78	NE	14.35	23.52	
7	0.000	2.050	73.80244	-1.167	1.686	454115.101	5427676.947					Rotated Grid Corners (initially: pick cells-pl)			
8	0.000	2.456	74.14364	-1.398	2.019	454114.870	5427677.280		Grid Corners	X	Y	X	Y		
9	0.000	2.862	47.6227	-1.629	2.353	454114.639	5427677.614		SE	27.00	0.00	SE	22	15.386	
10	0.000	3.268	22.59538	-1.860	2.687	454114.408	5427677.948		SW	0.00	0.00	SW	-0.012	0.017	
11	0.000	3.674	20.95218	-2.091	3.020	454114.177	5427678.281		NW	0.00	11.00	NW	-6.249	9.027	
12	0.000	4.080	4.896253	-2.322	3.354	454113.946	5427678.615		NE	27.00	11.00	NE	15.950	24.396	
13	0.000	4.485	-11.215	-2.553	3.688	454113.715	5427678.949								
14	0.000	4.891	-25.7295	-2.784	4.022	454113.484	5427679.283		Guess rotation angle						
15	0.000	5.297	-34.0084	-3.015	4.355	454113.253	5427679.616		-34.6956	degrees (enter)					
16	0.000	5.703	-41.1147	-3.246	4.689	454113.022	5427679.950		-0.60555	radians (calculated)					
17	0.000	6.109	-44.9324	-3.477	5.023	454112.791	5427680.284		Make objective cell (sqrt differences of corners)						
18	0.000	6.515	-52.9755	-3.708	5.356	454112.560	5427680.617		2.192632						
19	0.000	6.920	-62.4718	-3.939	5.690	454112.329	5427680.951								

- Plot the rotated values and adjust the rotation angle visually until the grid fits well.



- Fill in the 'Rotated Grid Corners' table ('picked' in figure) by pointing to appropriate cells in the rotated columns.
- To use Excel's SOLVER for nonlinear least squares improvement of your guess make a target cell with an objective function. I use the square root of the sum of the differences of each of the coordinate pairs:

$$=SQRT((M9-N3)^2+(M10-N4^2)+(M11-N5)^2+(M12-N6)^2+(N9-O3)^2+(N10-O4)^2+(N11-O5)^2+(N12-O6)^2)$$



- Following SOLVER, undo the translation step above by translating the rotated grid back to the GPS origin:
 1. $X_{translated} = X + \text{southwest corner GPS_X value}$
 2. $Y_{translated} = Y + \text{southwest corner GPS_Y value}$

